

CEVA TECHNOLOGY SYMPOSIUM SERIES

Enabling Intelligent Vision Processing at the Edge

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www.ceva-dsp.com

CV Market Trends

Mobile Market Trend



3D brings the fourth camera embedded in smartphones!



Y Developpement

| 3D Imaging & Sensing | www.yole.fr | ©2018

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Smartphone with Four Rear Cameras !

Computational photography features:

- 2x optical zoom
- Scene optimizer (19 modes)
- Manual depth of field adjusting
- Flaw detection (e.g. Eye Blink, Facial Blur, and backlight issues)
- And much more…

The camera is still the main highlighted feature
There is a need for a better image/video quality

Samsung Galaxy A9



Google Pixel 3 (&2) - Pixel Visual Core

Computational photography features:

- HDR+, 5 images with 1/10th the power consumption
- Complex imaging and machine learning tasks
- Super resolution zoom

Night sight





A foreground and background mask created by Google's neural network.



Depth Map data captured using a PDAF camera and the resulting blur map for the final image.



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CEVA Proprietary Information

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Google Pixel 3 – Night Sight





Allows for incredibly detailed pictures to be captured in low-light situations (without the aid of a flash)

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OPPO Find-X - 3D Structured Light Technology



- Global shipments of smartphones featuring 3D sensing technology are expected to top over 100 million units in 2018*
 - Apple serving as the primary vendor and following by Xiaomi, Oppo and Vivo



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(*) according to an estimate of China-based Sigmaintell

Creates a millimeter-scale 3D face depth map for safer unlock

Creates 3D stereo model of the face to perform 3D personality beauty

3D Vision Technology



3D vision is a key technology in the fields of human-computer interaction, face recognition, AR/VR, assisted driving, etc.

Automotive	Healthcare	
Robotics	3D Scanning/Printing	
3D Metrology	Gaming	
Retail	AR/VR	

3D imaging & sensing revenue breakdown by markets

(Source: 3D Imaging & Sensing 2018, Yole Développement, June 2018)



Security Smart Home

SLAM* (combined with AI)





https://www.vincross.com/hexa



(*) Simultaneous Localization And Mapping

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What do we Need to Make it Happen?



VR market faces many challenges

What do we need to "cross the chasm"?



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Mobile VR Challenges

- Strong Computing Power
 Connected to a PC
 Latoney issues
 - Latency issues
- Easy of use
 - Inside-out tracking
 - Power consumption
- Quality content



Long battery life Equipped with a **3200** mAh lithium polymer battery, can play about **3** hours.







CEVA Imaging & Vision

Industry Recognition



Linley Group

CEVA-XM4 awarded Linley's "Best Processor IP" in 2015





Vision System Design

 CEVA-XM6 awarded "Innovator Gold Awards" in 2018





Enable Comprehensive Vision and Al Solutions



- Computational photography and computer vision applications, delivering a human-like visual perception
- Intelligent processing applications, delivering a human-like smart devices

FVA

Enabling power-efficient, intelligent devices for a range of end markets, including mobile, consumer, automotive, industrial and IoT



CEVA Vision and Imaging DSP as 'Enabler' for Better Image and Video Quality





Rockchip RK1608

Technology Features

- Dual CEVA-XM4 @ 600MHz
- Frame based process, rather than line based in ISP
- Multi frame process, RAW domain, better quality than YUV domain
- Faster than AP process, 200ms process Multi frame de-noise
- No impact AF/AWB, just fine tune AE of ISP

http://www.rock-chips.com/a/en/News/Press_Releases/2017/0227/836.html



Rackchi

RK1608



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Motorola X

Galaxy S7

somacbeth CelorChecker** Color Re

retagmacpeth ColorChecker™ Color Renditio

@ 5 LUX

iPhone 7 Plus

gretagmac6eth ColorChecker™ Color Rendition Chart

ASUS Zenfone 3 Zoom

SLAM Technology

What is SLAM?



Simultaneous Localization And Mapping

Find sensor position in space (6DoF) while mapping the environment



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SLAM Technology



In order for computer vision application to relate to the real environment the device must find it's position in space accurately



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Industry Using SLAM



- Mobile device localization
- Automotive
- Drones
- Enabler for AR/VR application
 Apple's ARKit
 Google's ARCore
 ARCore

SLAM is an essential technology for AR to accurately position virtual objects in tracked scenes

SLAM Solutions



Various visual SLAM solution vendors



All share similar building blocks when it comes heavy processing

Each vendor have it's own propriety high level logic and tuning



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CEVA's SLAM SDK



Accelerate heavy processing using efficient vector DSP

- Easy seamless integration with standard APIs
- Generic modules supports various sensors
 - Mono, Stereo, TOF
- Feature set
 - Image processing
 - Feature detection, extraction and matching
 - 3D point processing
 - Complex math operation

CEVA's SLAM SDK - Integration



- Two main deign goals:
 - Optimized CV functions
 - Easy integration with existing solutions Offload framework

CEVA-XM

Host



Example – ORB SLAM2



ORB-SLAM (openCV,Eigen)

ORB-SLAM (CEVA-SLAM-SDK)



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Example – ORB SLAM2



Accuracy Analysis

Trajectory



Error Statistics Analysis

Relative Error (% Of Range)	Open Source	CEVA SLAM-SDK
Mean	0.6	0.5
Median 50%	0.65	0.5
Median 90%	0.9	0.8

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CEVA's Software Ecosystem Enable Fast Time-to-Market

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Thank You



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